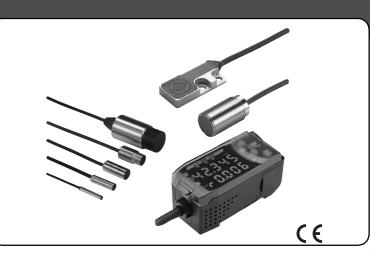
## Smart Sensors (Inductive Displacement Type)

# **ZX-E** Series

Smart Sensors that use the eddy current method are now available. Develop new applications with sub-micron sensing technology.



## **Ordering Information**

### Sensors

### Sensor Heads

| Shape                       | Dimensions       | Sensing distance | Resolution *1 | Model          |
|-----------------------------|------------------|------------------|---------------|----------------|
| Cylindrical                 | 3 dia. x 18 mm   | 0.5 mm           | 1 μm          | ZX-EDR5T       |
|                             | 5.4 dia. x 18 mm | 1 mm             |               | ZX-ED01T *2    |
|                             | 8 dia. x 22 mm   | 2 mm             |               | ZX-ED02T *2    |
| Screw-shaped                | M10 x 22 mm      |                  |               | ZX-EM02T *2    |
|                             | M18 x 46.3 mm    | 7 mm             |               | ZX-EM07MT *2   |
| Flat                        | 30 x 14 x 4.8 mm | 4 mm             |               | ZX-EV04T *2 *3 |
| Heat-resistant, cylindrical | M12 x 22 mm      | 2 mm             |               | ZX-EM02HT *4   |

\*1: For an average count of 4,096.

\*2: Models with Protective Spiral Tubes are also available. Add a suffix of "-S" to the above model numbers when ordering. (Example: ZX-ED01T-S)

\*3: Be sure to use ZX-EDA Amplifier Unit version 1,200 or later with the ZX-EV04.

\*4: Be sure to use ZX-EDA Amplifier Unit version 1,300 or later with the ZX-EM02H.

### **Amplifier Units**

| Appearance | Power supply | Output type | Model    |
|------------|--------------|-------------|----------|
| 2          | DC           | NPN         | ZX-EDA11 |
|            |              | PNP         | ZX-EDA41 |

Note: Compatible connection with the Sensor Head.

## Accessories (Order Separately)

### **Calculating Unit**

| Appearance | Model   |
|------------|---------|
|            | ZX-CAL2 |

### **Amplifier Mounting Brackets**

| Appearance | Model   | Remarks                            |
|------------|---------|------------------------------------|
|            | ZX-XBE1 | Attached to<br>each Sensor<br>Head |
|            | ZX-XBE2 | For DIN track mounting             |

## SmartMonitor Sensor Setup Tool for Personal Computer Connection

| Appearance  | Name  | Model            |
|-------------|---|------------------|
|             | ZX-series Communica-<br>tions Interface Unit                        | ZX-SF11          |
| +<br>CD-ROM | ZX-series Communica-<br>tions Interface Unit<br>+<br>Setup Software | ZX-<br>SFW11EV3* |
| CD-ROM      | ZX-series Sensor Setup<br>and Logging Software                      | ZX-SW11EV3       |

\* The ZX-SFW11EV3 SmartMonitor can be used only to set functions and monitor waveforms.

#### Cables with Connectors on Both Ends (for Extension)\*

| Cable length | Model   | Quantity |
|--------------|---------|----------|
| 1 m          | ZX-XC1A | 1        |
| 4 m          | ZX-XC4A |          |
| 8 m          | ZX-XC8A |          |

\* Robot cable models are also available. The model numbers are  $ZX-XC\square R$ .

## **Specifications**

### ■ Sensor Heads

|   |                | Model   | ZX-EDR5T  | ZX-ED01T   | ZX-ED02T/<br>EM02T | ZX-EM07MT     | ZX-EV04T                 | ZX-EM02H             |
|---|----------------|---|---|--|--------------------|---------------|--------------------------|----------------------|
| Measurement range   |                | 0 to 0.5 mm   | 0 to 1 mm   | 0 to 2 mm  | 0 to 7 mm          | 0 to 4 mm     | 0 to 2 mm                |                      |
| Sensing object  |                | Magnetic metals (Measurement ranges and linearities are different for non-magnetic metals. Refer to<br>Engineering Data on page 4.) |   |  |                    |               |                          |                      |
| Standard reference object                                   |                | 18×18×3 mm  | 30×30×3 mm 60×60×3 mm   |  | 45×45×3 mm         |               |                          |                      |
|   |                | Material: ferrous (   | Material: ferrous (S50C)  |  |                    |               |                          |                      |
| Resolution *1   |                |   | 1 μm  |  |                    |               |                          |                      |
| Linearity *2  |                |   | ±0.5% F.S.  |  |                    |               |                          | ±1.0% F.S. *5        |
| Linear output rang  | ge             |   | Same as measure   | ement range.   |                    |               |                          |                      |
| Temperature characteristic *3<br>(including Amplifier Unit) |                | 0.15% F.S./°C   | 0.07% F.S./°C   | 0.07% F.S./°C  |                    |               |                          |                      |
| Ambient temper- Operating *4                                |                | ng *4   | 0 to 50°C (with no  | -10 to 60°C (wit   | th no icing or cor | ndensation)   |                          | -10 to 200°C         |
| ature Storage *4  |                | icing or conden-<br>sation)   | -20 to 70°C (with no icing or condensation)                                     |  |                    | –20 to 200°C  |                          |                      |
| Ambient humidity  |                |   | Operating and storage: 35% to 85% (with no condensation)                        |  |                    |               |                          |                      |
| Insulation resistar   | nce            |   | 50 MΩ min. (at 500 DC)  |  |                    |               |                          |                      |
| Dielectric strength   | า              |   | 1,000 VAC, 50/60 Hz for 1 min between charged parts and case                    |  |                    |               |                          |                      |
| Vibration resistan  | ce (dest       | ruction)  | 10 to 55 Hz with 1.5-mm double amplitude for 2 h each in X, Y, and Z directions |  |                    |               |                          |                      |
| Shock resistance  | (destruc       | tion)   | 500 m/s <sup>2</sup> , 3 times each in X, Y, and Z directions                   |  |                    |               |                          |                      |
| Degree of protecti  | on (Sen        | sor Head)   | IEC60529, IP65  | IEC60529, IP67   |                    |               |                          | IEC60529,<br>IP60 *6 |
| Connection metho  | bd             |   | Connector relay (   | nnector relay (standard cable length: 2 m)               |                    |               |                          |                      |
| Weight (packed state)                                       |                |   | Approx. 120 g   | Approx. 140 g  |                    | Approx. 160 g | Approx. 130 g            | Approx. 160 g        |
| Materials   | Sensor<br>Head | Case  | Brass   | Stainless steel  | Brass              |               | Zinc (nickel-<br>plated) | Brass                |
|   |                | Sensing<br>surface  | Heat-resistant AB   | S  |                    |               |                          | PEEK                 |
| Preamplifier  |                | PES   |   |  |                    |               |                          |                      |
| Accessories   |                |   | Amplifier Mountin   | mplifier Mounting Brackets (ZX-XBE1), Instruction Manual |                    |               |                          |                      |

**ZX-E Series** Smart Sensors (Inductive Displacement Type)

\*1:Resolution: The resolution is the deviation (±3σ) in the linear output when connected to the ZX-EDA Amplifier Unit. The above values indicate the deviations observed 30 minutes after the power is turned ON.

(The resolution is measured with OMRON's standard reference object at 1/2 of the measurement range with the ZX-EDA set for the maximum average count of 4,096 per period.)

The resolution is given at the repeat accuracy for a stationary workpiece, and is not an indication of the distance accuracy. The resolution may be adversely affected under strong electromagnetic fields.

- \*2: Linearity: The linearity is given as the error in an ideal straight line displacement output when measuring the standard reference object. The linearity and measurement values vary with the object being measured.
- \*3: Temperature characteristic: The temperature characteristic is measured with OMRON's standard reference object at 1/2 of the measurement range.
- \*4: The ambient temperature given is only for the sensor head. It is -10 to 60°C for the preamp.
- \*5: The value given is for an ambient temperature of 25°C.
- \*6: Do not use in moist environments because the case is not waterproof.

### ■ Amplifier Units

| Model   | ZX-EDA11   | ZX-EDA41   |  |
|---|--|--|--|
| Measurement period                              | 150 μs   |  |  |
| Possible average count settings *1              | 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1,024, 2,048, o   | r 4,096  |  |
| Linear output *2                                | Current output: 4 to 20 mA/F.S., Max. load resistance  | ce: 300 Ω  |  |
|   | Voltage output: $\pm$ 4 V ( $\pm$ 5 V, 1 to 5 V *3), Output impe   | edance: 100 Ω  |  |
| Judgement outputs<br>(3 outputs: HIGH/PASS/LOW) | NPN open-collector outputs, 30 VDC, 50 mA max.<br>Residual voltage: 1.2 V max.   | PNP open-collector outputs, 30 VDC, 50 mA max.<br>Residual voltage: 2 V max.   |  |
| Zero reset input, timing input, reset           | ON: Short-circuited with 0-V terminal or 1.5 V or  | ON: Supply voltage short-circuited or supply volt-   |  |
| input, judgement output hold input              | less   | age within 1.5 V   |  |
|   | OFF: Open (leakage current: 0.1 mA max.)   | OFF: Open (leakage current: 0.1 mA max.)   |  |
| Function  | <ul> <li>Linearity adjustment (materials selection)</li> <li>Display reverse</li> <li>Number of display digit changes</li> <li>Bottom hold, peak-to-peak hold</li> <li>Average hold</li> <li>Initial reset</li> <li>OFF-delay timer</li> <li>Automatic teaching</li> <li>Reset input</li> <li>Linear output correction</li> <li>(A-B) calculation</li> </ul> | <ul> <li>Peak hold</li> <li>Self-bottom hold</li> <li>Zero reset</li> <li>ON-delay timer</li> <li>Previous value comparison</li> <li>Id value setting</li> <li>Timing inputs</li> <li>tput hold input</li> <li>Monitor focus</li> <li>ons *4</li> <li>(A+B) calculations *4</li> </ul> |  |
| Indications                                     | Judgement indicators: High (orange), pass (green),<br>7-segment sub-digital display (yellow), power ON (g  | reen), zero reset (green), enable (green)  |  |
| Voltage influence<br>(including Sensor)         | 0.5% F.S. of linear output value at $\pm 20\%$ of power su   | upply voltage  |  |
| Power supply voltage                            | 12 to 24 VDC $\pm$ 10%, Ripple (p-p): 10% max.   |  |  |
| Current consumption                             | 140 mA max. with power supply voltage of 24 VDC  | ,  |  |
| Ambient temperature                             | Operating and storage: 0 to 50°C (with no icing or co  | ,  |  |
| Ambient humidity                                | Operating and storage: 35% to 85% (with no conder  | nsation)   |  |
| Insulation resistance                           | 20 MΩ min. (at 500 DC)   |  |  |
| Dielectric strength                             | 1,000 VAC, 50/60 Hz for 1 min  |  |  |
| Vibration resistance (destruction)              | 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in X, Y, and Z directions  |  |  |
| Shock resistance (destruction)                  | 300 m/s <sup>2</sup> , 3 times each in 6 directions (up, down, left, right, forward, backward)   |  |  |
| Connection method                               | Prewired (standard cable length: 2 m)  |  |  |
| Weight (packed state)                           | Approx. 350 g  |  |  |
| Materials                                       | Case: PBT (polybutylene terephthalate), Cover: Poly  | ycarbonate   |  |
| Accessories                                     | Instruction Manual   |  |  |
|   |  |  |  |

\*1:The response speed of the linear output is calculated as the measurement period × (average count setting + 1) (with fixed sensitivity). The response speed of the judgement outputs is calculated as the measurement period × (average count setting + 1) (with fixed sensitivity).

\*2: The output can be switched between a current output and voltage output using a switch on the bottom of the Amplifier Unit.

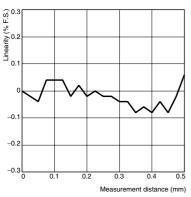
\*3: Setting is possible via the monitor focus function.

\*4: A Calculating Unit (ZX-CAL2) is required.

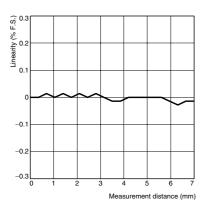
## **Engineering Data (Typical)**

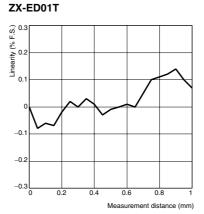
#### Measurement Distance vs. Linearity (with Linearity Adjusted for Standard Sensing Object)

#### ZX-EDR5T

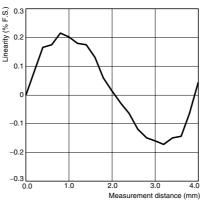


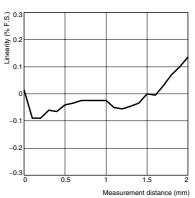
#### **ZX-EM07MT**





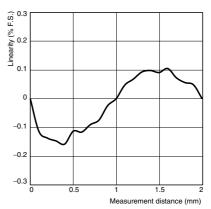






ZX-ED02T/ZX-EM02T





#### Size of Sensing Object vs. Linearity (with Linearity Adjusted for Each Sensing Object) ZX-EDR5T ZX-ED01T

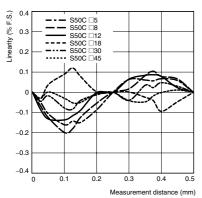
0.6

0.5

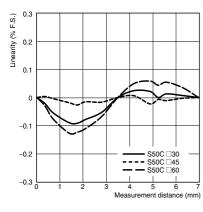
0.4

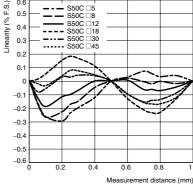
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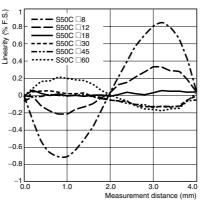
#### **ZX-EM07MT**





S50C □5 S50C □8

#### ZX-EV04T



#### ZX-EM02HT

ZX-ED02T/ZX-EM02T

S50C S50C S50C S50C S50C S50C

8-----

1.5

Measurement distance (mm)

0.5

(; 1.0 ⊗ ⊔ ⊗ 0.8

0.4

0.2

-0.2

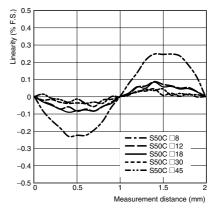
-0.4

-0.6

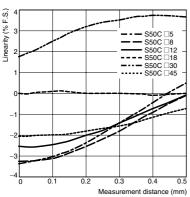
-0.8

-1.0

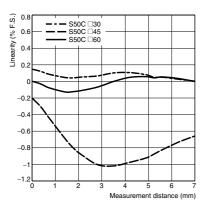
Linearity 0.6

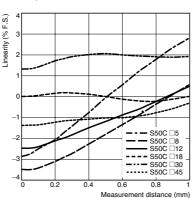


#### Size of Sensing Object vs. Linearity (with Linearity Adjusted for Standard Sensing Object) ZX-EDR5T ZX-ED01T

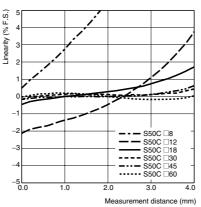




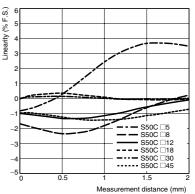




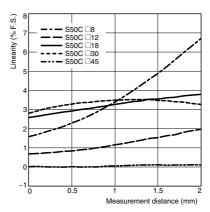




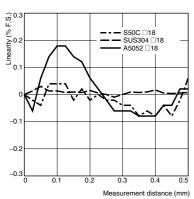
#### ZX-ED02T/ZX-EM02T



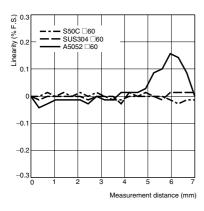
#### ZX-EM02HT

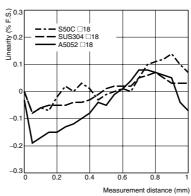


#### Material of Sensing Object vs. Linearity (with Linearity Adjusted for Each Sensing Object) ZX-EDR5T ZX-ED01T

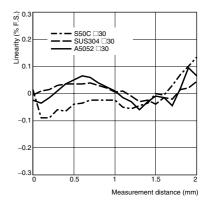


#### ZX-EM07MT

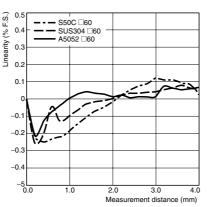




#### ZX-ED02T/ZX-EM02T

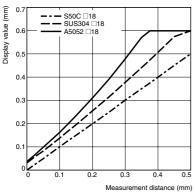


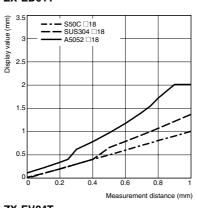
#### ZX-EV04T

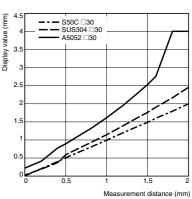


**ZX-E Series** Smart Sensors (Inductive Displacement Type)

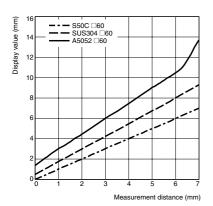
## Material of Sensing Object vs. Linearity (with Linearity Adjusted for Standard Sensing Object and Iron) ZX-EDR5T ZX-ED01T ZX-ED02T/ZX-EM02T





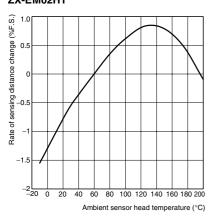


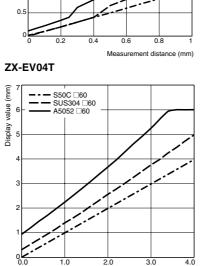
ZX-EM07MT



Temperature Characteristics ZX-EM02HT

6

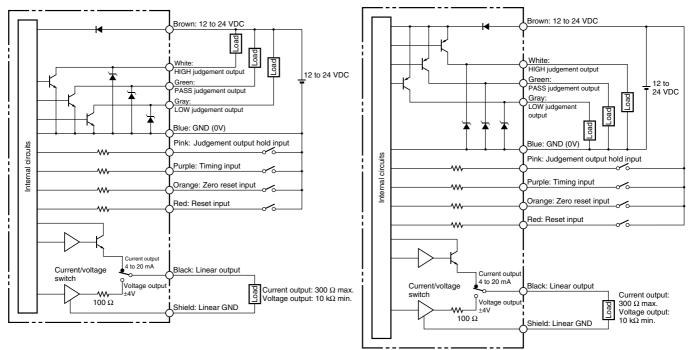




Measurement distance (mm)

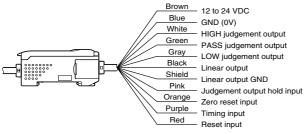
## I/O Circuit Diagrams

#### NPN Amplifier Unit: ZX-EDA11



**PNP Amplifier Unit: ZX-EDA41** 

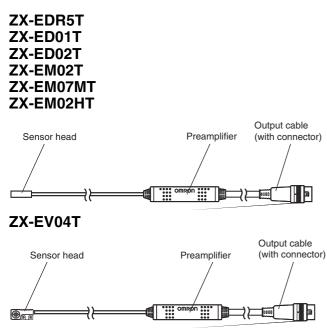
## **Connections: Amplifier Unit**



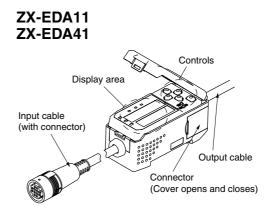
- Note 1. Use a separate stabilized power supply for the Amplifier Unit, particularly when high resolution is required.
  - Wire the Unit correctly. Incorrect wiring may result in damage to the Unit. (Do not allow wiring, particularly the linear output, to come into contact with other lines.)
  - 3. Use the blue (0-V) line for the power supply and use the shield wire (linear output ground) together with the black (linear output) line for linear output. Each of these grounds must be used for the designed purpose. When not using the linear output, connect the linear output ground to the 0-V ground.

## **Part Names**

### <u>Sensors</u>

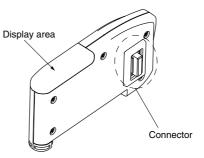


### **Amplifier Units**



### **Calculating Unit**

### ZX-CAL2



## Precautions

### Design Precautions

Conform to the specified ratings and performance. Refer to *Specifications* on page 2 for details.

Objects of certain materials or shapes may not be detectable, or the detection accuracy may not be sufficiently high.

### **Environment**

Do not operate the product in locations subject to flammable or explosive gases.

In order to ensure safe operation and maintenance, do not install the product in the vicinity of high-voltage devices or power equipment.

### ■ Wiring

Do not use the product at voltages exceeding the rated values. Doing so may result in damage.

Do not connect the product to an AC power supply or connect the power supply in reverse.

Do not short-circuit the load for open-collector output.

### Correct Use <u>Design Precautions</u>

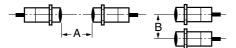
#### **Power Supplies**

Allow a warm-up period of approximately 30 minutes after turning ON the power supply.

#### **Mutual Interference**

Up to 5 Sensor Heads can be used together by connecting the ZX-CAL2 Calculating Unit between Amplifier Units.

When installing Sensor Heads facing each other or in parallel, separate them by the minimum distances given in the table below.



#### **Mutual Interference**

| Model     | Α      | В           |  |
|-----------|--------|-------------|--|
| ZX-EDR5T  | 5 mm   | 20 (3.1) mm |  |
| ZX-ED01T  | 10 mm  | 50 (5.4) mm |  |
| ZX-ED02T  | 20 mm  | 50 (8) mm   |  |
| ZX-EM02T  | 20 mm  | 50 (10) mm  |  |
| ZX-EM07MT | 100 mm | 150 (30) mm |  |
| ZX-EV04T  | 80 mm  | 50 (14) mm  |  |
| ZX-EM02HT | 20 mm  | 50 (12) mm  |  |

**Note:** The figures in parentheses apply when the mutual interference prevention function is used.

### Compatibility

Sensors and Amplifier Units are mutually compatible. Sensors can be added or replaced individually.

#### Influence of High-frequency Electromagnetic Fields

Using the product in the vicinity of devices that generate high-frequency electromagnetic fields, such as ultrasonic cleaning equipment, high-frequency generators, transceivers, mobile phones, and inverters, may result in malfunction. Do not lay the power cable for the product together with or in the same duct as high-voltage lines or power lines. Doing so may result in incorrect operation or damage due to induction.

Do not connect or disconnect connectors while the power is ON. Doing so may result in damage.

### Adjustment

### Setting

When setting threshold values, ensure that the Amplifier Unit's judgement output hold input line is ON so that there is no judgement output to external devices.

### Other Precautions

Do not attempt to disassemble, repair, or modify the product.

Dispose of the product using standard procedures for industrial waste.

These Sensors are not compatible with the ZX-L $\Box$  Smart Sensors (laser type). Do not connect combinations of ZX-E $\Box$  Smart Sensors and ZX-T $\Box$  Smart Sensors.

### **Influence of Metallic Objects**

When installing the product, separate it from metallic objects by the distances shown below.



#### **Influence of Metallic Objects**

| Model          | d               | D      |
|----------------|-----------------|--------|
| ZX-EDR5T       | 8 mm            | 9 mm   |
| ZX-ED01T       | 10 mm           |        |
| ZX-ED02T/EM02T | 12 mm           |        |
| ZX-EM07MT      | 55 mm           | 20 mm  |
| ZX-EV04T       | 16 	imes 32  mm | 4.8 mm |
| ZX-EM02HT      | 18 mm           | 9 mm   |

### <u>Wiring</u>

### **Wiring Check**

After wiring is completed, before turning ON the power, confirm that the power supply is connected correctly, that there are no faulty connections, such as load short-circuits, and that the load current is correct. Incorrect wiring may result in failure.

#### **Cable Extension**

Do not extend the cable for the Sensor and the Amplifier Unit to a length exceeding 10 m. Use a ZX-XC A Extension Cable (sold separately) to extend the Sensor's cable. Extend the Amplifier Unit's cable using a shielded cable of the same type.

#### **Power Supply**

When using a commercially available switching regulator, ground the FG (frame ground) terminal.

If the power supply line is subject to surges, connect a surge absorber that meets the conditions of the operating environment.

### **Calculating Unit**

When using a Calculating Unit, connect the linear output ground of the corresponding Amplifier Unit.

#### Connectors

Do not connect or disconnect connectors while the power is ON.

Be sure hold to connectors by the cover when connecting or disconnecting.

### <u>Mounting</u> Handling

When mounting the Sensor Head, do not apply excessive shock by, for example, using a hammer. Doing so may result in damage or a reduction in the level of water-proofing. Also, there are screw-shaped models that require a toothed washer to allow for a tolerance in the tightening torque for the nut.

When using a heat-resistant model like the ZX-EM02HT, develop designs that account for thermal expansion due to rising sensing object temperature so the sensing object will never touch the sensing surface. Also note that any sudden rise in temperature will shorten the service life of the product.

### **Tightening Torque**

Do not apply excessive torque when tightening the nut. Use a toothed washer if necessary.

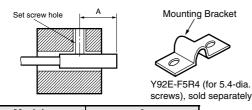


| Model     | Tightening torque |
|-----------|-------------------|
| ZX-EM02T  | 15 N·m            |
| ZX-EM07MT |                   |
| ZX-EM02HT | 59 N∙m            |

Note: The above figure applies for use with a toothed washer.

Mounting Cylindrical Models:

Tighten set screws with a tightening torque of 0.2 N·m max.



| Model    | Α           |
|----------|-------------|
| ZX-EDR5T | 9 to 18 mm  |
| ZX-ED01T |             |
| ZX-ED02T | 11 to 22 mm |

### Installation Location

Do not install the product in the following locations.

- · Locations subject to temperatures outside the specified range
- Locations subject to condensation due to sudden temperature
- changesLocations subject to humidity levels outside range 35% to 85%
- Locations subject to corrosive or flammable gases
- Locations subject to dust, salts, or metallic powder.
- · Locations directly subject to vibrations and shocks
- Locations subject to direct sunlight
- · Locations subject to splashes of water, oil, or chemicals
- · Locations subject to strong electromagnetic or electrical fields

#### **Maintenance and Inspection**

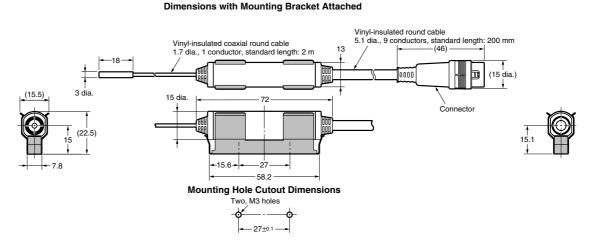
- Be sure to turn OFF the power supply before adjusting or removing
- the Sensor Head.Cleaning:
- Do not use thinners, benzine, acetone, or kerosene for cleaning.

## Dimensions

### **Sensors**

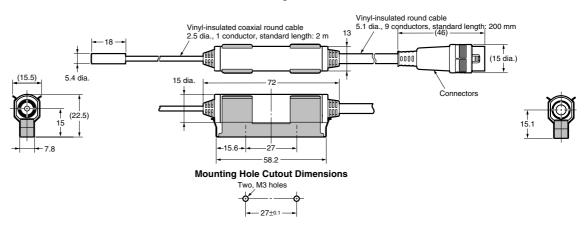
#### **Sensor Heads**

ZX-EDR5T



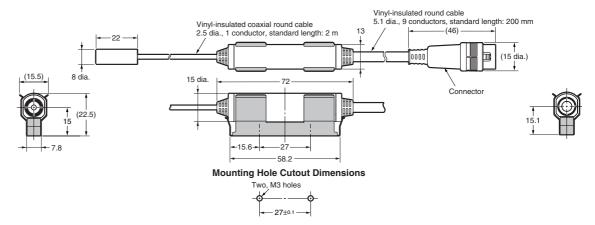
ZX-ED01 T

Dimensions with Mounting Bracket Attached



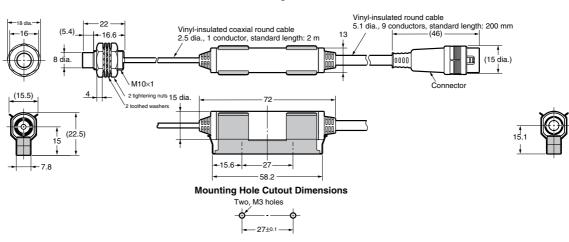
ZX-ED02T

#### Dimensions with Mounting Bracket Attached

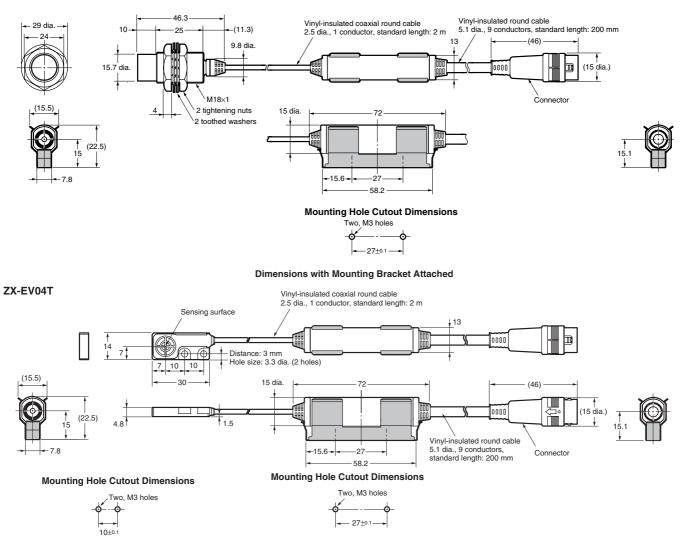


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#### **Dimensions with Mounting Bracket Attached**



ZX-EM07MT

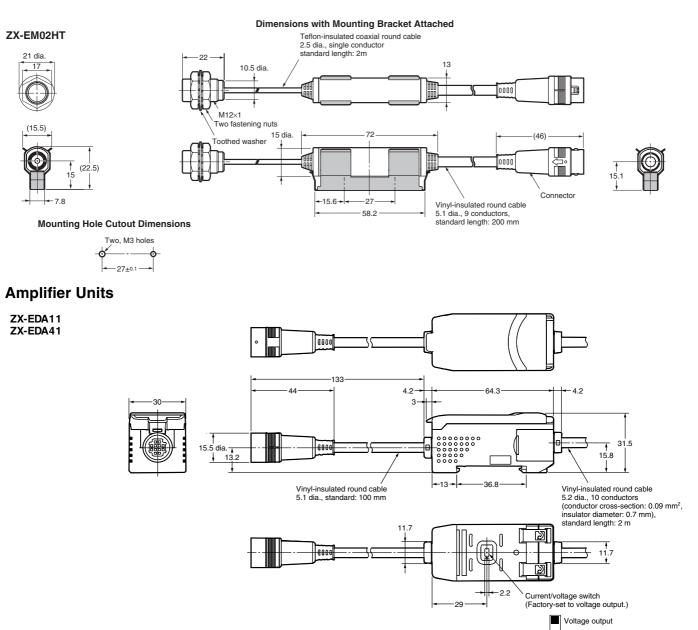


#### Dimensions with Mounting Bracket Attached

12 **ZX-E Series** Smart Sensors (Inductive Displacement Type)

### OMRON

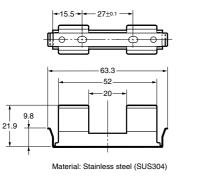
13

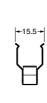


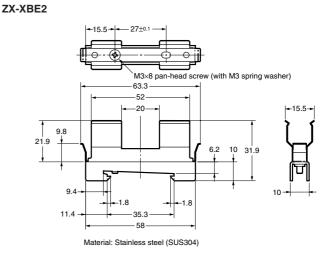
### Accessories (Sold Separately)

### **Preamplifier Mounting Bracket**

ZX-XBE1

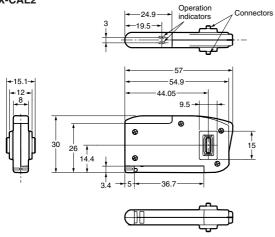






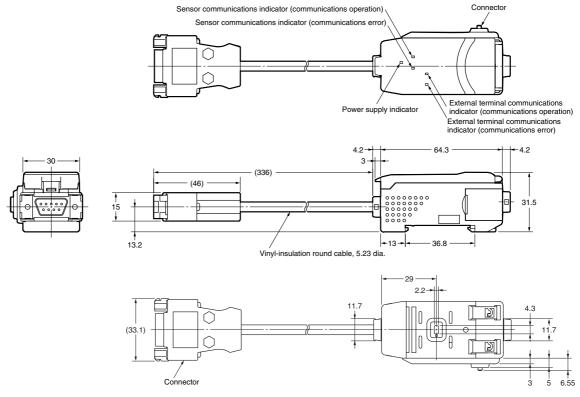
### **Calculating Unit**

ZX-CAL2



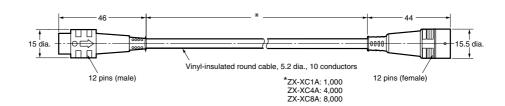
#### **ZX-series Communications Interface Unit**





### Cables with Connectors on Both Ends (for Extension)

ZX-XC1A (1 m) ZX-XC4A (4 m) ZX-XC8A (8 m)



#### ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

This document provides information mainly for selecting suitable models. Please read the manual carefully for information that the user must understand and accept before purchase, including information on warranty, limitations of liability, and precautions.

#### Cat. No. E331-E1-03 In the interest of product improvement, specifications are subject to change without notice.

#### OMRON Corporation Industrial Automation Company

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